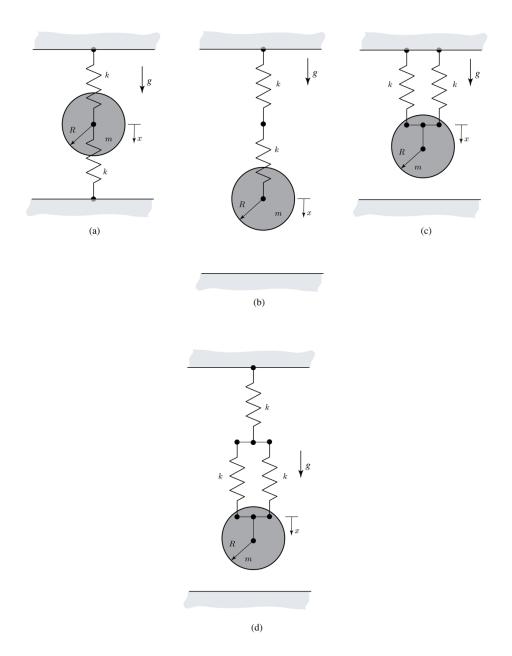
ME 563-Fall 2025

Homework No. 1

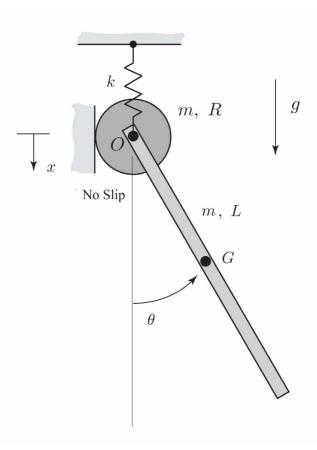
Due: September 10, 2025 11:59 pm on Gradescope

Consider each one-degree-of-freedom system shown below consisting of springs of stiffnesses k, and cylinders of masss m.



- a) Determine the equivalent spring stiffness for each system. Do this by drawing a FBD of each mass and spring as needed.
- b) Determine the equilibrium position of the system, x_{st} , for each system. Which system deflects the most due to gravity?

Consider the two-degree-of-freedom system shown below made up of a rod G and a cyilnder O each of mass m, each of mass m. The rotation of the rod is denoted by θ . The spring is unstretched when $x=\theta=0$. The cylinder rolls without slip.

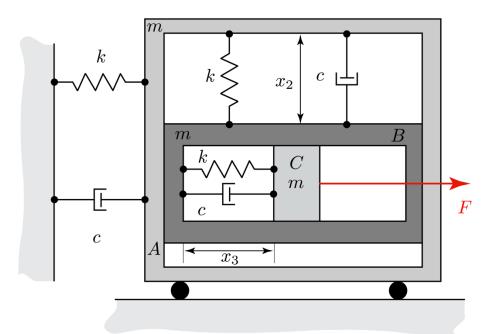


- a) Draw individual free body diagrams of each body.
- b) Use the Newton- Euler formulation to derive two differential equations of motion for the system. Your final equations should not include any forces of reaction
- c) Determine the x and θ at equilibrium.

Consider the three-degree-of-freedom system shown below made up of three particles A, B, and C, each of mass m, with system moving within a horizontal plane. Let x_1 , describe the absolute motion of particle A, x_2 describe the motion of paticle B relative to A and A3 describe the motion of particle A5. All the springs are unstretched when A6. Assume all surfaces to be smooth.

- a) Draw individual free body diagrams of each particle.
- b) Use the Newton- Euler formulation to derive three differential equations of motion for the system. Your final equations should not include any forces of reaction.
- c) Write the equations of motion derived in b) in matrix form. Identify the mass, damping, and stiffness matrices in these equations.





Consider the system below: it consists of a drum of mass of m, and inner radius R, an outer radius 2R and a centroidal of inertia I_O . A spring of stiffness k connects the center of the drum O to a fixed wall. Block A has a mass of m. The inner surface of the disk rolls without slipping on the ground at point C. The cable does not slip on the outer radius of the drum. A force F acts to the right at the center of the drum O. Let ϕ be the rotation angle for the drum. The spring is unstretched when $\phi=0$.

- a) Using the Newton-Euler formulation, determine the equations of motion for the system using the coordinate ϕ . Draw the free body diagrams of the drum and block individually before writing down the Newton-Euler equations.
- b) Using the <u>power equation formulation</u>, determin the equations of motion for the system using the coordinate ϕ . Draw a free body diagram of the entire system before writing down the power equation.

