

Equation sheet

$$\begin{aligned}\vec{v}_P &= \dot{x}\hat{i} + \dot{y}\hat{j} \\ &= v_P\hat{e}_t \\ &= \dot{r}\hat{e}_r + r\dot{\theta}\hat{e}_\theta \\ &= \vec{v}_B + \vec{\omega} \times \vec{r}_{P/B} \\ &= \vec{v}_B + (\vec{v}_{P/B})_{rel} + \vec{\omega} \times \vec{r}_{P/B} \\ &= \vec{v}_B + \vec{v}_{P/B}\end{aligned}$$

$$\begin{aligned}\vec{a}_P &= \ddot{x}\hat{i} + \ddot{y}\hat{j} \\ &= \dot{v}_P\hat{e}_t + \frac{v^2}{\rho}\hat{e}_n \\ &= (\ddot{r} - r\dot{\theta}^2)\hat{e}_r + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{e}_\theta \\ &= \vec{a}_B + \vec{\alpha} \times \vec{r}_{P/B} - \omega^2\vec{r}_{P/B} \\ &= \vec{a}_B + (\vec{a}_{P/B})_{rel} + \vec{\alpha} \times \vec{r}_{P/B} + 2\vec{\omega} \times (\vec{v}_{P/B})_{rel} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{P/B}) \\ &= \vec{a}_B + \vec{a}_{P/B}\end{aligned}$$

$$\sum \vec{F} = m\vec{a}_G$$

$$\sum \vec{M}_A = I_A\vec{\alpha} + m\vec{r}_{G/A} \times \vec{a}_A \quad ; \quad I_A = I_G + md^2$$

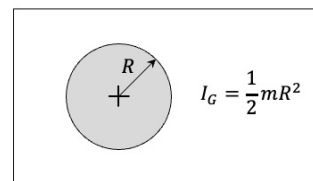
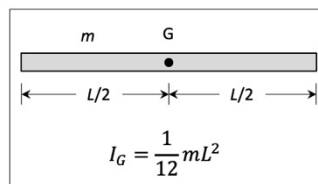
$$T_1 + V_1 + U_{1 \rightarrow 2}^{(nc)} = T_2 + V_2$$

$$T = \frac{1}{2}mv_A^2 + \frac{1}{2}I_A\omega^2 + m\vec{v}_A \cdot (\vec{\omega} \times \vec{r}_{G/A})$$

$$V_{gr} = mgh_G$$

$$V_{sp} = \frac{1}{2}k\Delta^2$$

$$U_{1 \rightarrow 2}^{(nc)} = \int_1^2 (\vec{F} \cdot \hat{e}_t) ds$$



$$\int_1^2 \sum \vec{F} dt = m\vec{v}_{G2} - m\vec{v}_{G1} \quad ; \quad e = - \left[\frac{v_{Bn2} - v_{An2}}{v_{Bn1} - v_{An1}} \right]$$

$$\int_1^2 \vec{M}_A dt = \vec{H}_{A2} - \vec{H}_{A1} \quad ; \quad \vec{H}_A = \vec{r}_{P/A} \times (m\vec{v}_A) \quad ; \quad \vec{H}_A = I_A\vec{\omega}$$

$$M\ddot{x} + C\dot{x} + Kx = F_0 \sin \omega t \quad \Rightarrow \quad \ddot{x} + 2\zeta\omega_n\dot{x} + \omega_n^2 x = (F_0 / M) \sin \omega t$$

$$x_C(t) = e^{-\zeta\omega_n t} (C \cos \omega_d t + S \sin \omega_d t) \quad ; \quad \omega_d = \omega_n \sqrt{1 - \zeta^2} \quad [\text{for } 0 \leq \zeta < 1]$$

$$x_P(t) = A \sin \omega t + B \cos \omega t$$