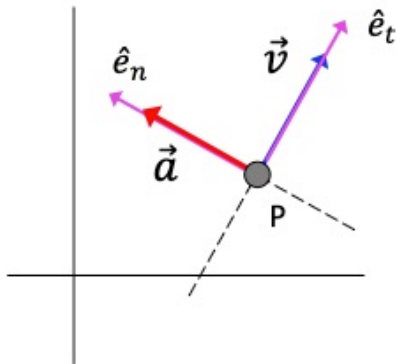


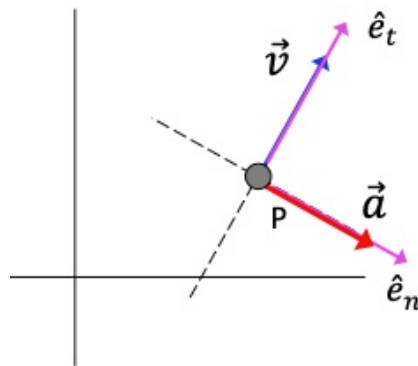
Given the direction of the velocity \vec{v} of point P, as shown in the figures below. For each of the six situations below, sketch the path unit vectors \hat{e}_t and \hat{e}_n , along with the acceleration vector \vec{a} .

Recall: $\vec{a} = v\hat{e}_t + \frac{v^2}{\rho}\hat{e}_n$.

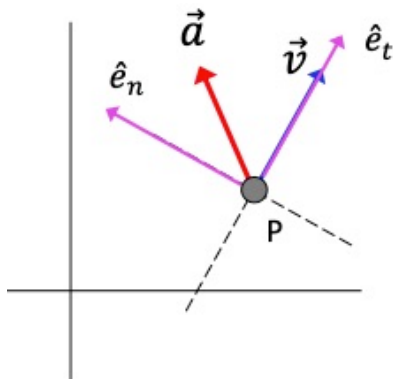
a) P having constant speed and turning left



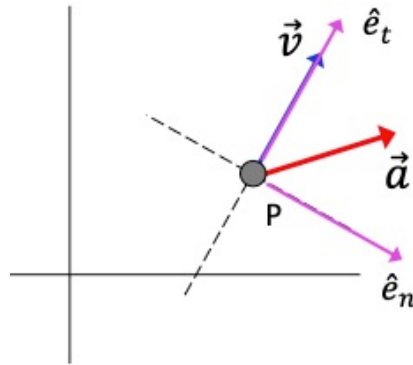
b) P having constant speed and turning right



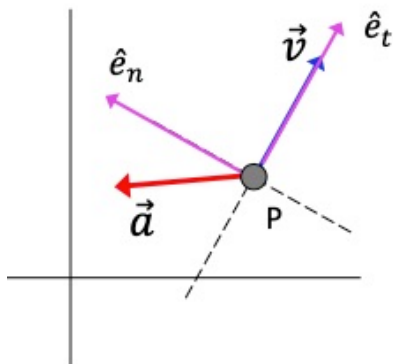
c) P increasing in speed and turning left



d) P increasing in speed and turning right



e) P decreasing in speed and turning left



f) P decreasing in speed and turning right

