## Question C3.1

Particle P moves on the top horizontal surface of a disk that is rotating in a clockwise sense about a vertical axis with a rate of $\Omega=5 \mathrm{rad} / \mathrm{s}$. The position of P is described in terms of a set of Cartesian components $x_{P}$ and $y_{P}$ measured relative to the disk. When $\left(x_{P}, y_{P}\right)=(4,3) \mathrm{ft}$, the velocity of $P$ as seen by a stationary observer is: $\vec{v}_{P}=(10 \hat{i}-20 \hat{j}) \mathrm{ft} / \mathrm{s}$. Describe the velocity of P as seen by an observer on the disk.



Question C3.2
A disk is pinned to ground at its center $O$ with the disk rotating clockwise at a constant rate of $\Omega=3 \mathrm{rad} / \mathrm{s}$. Block P is traveling to the left along a straight path toward O with a constant speed of $v_{P}=20 \mathrm{ft} / \mathrm{s}$. Determine the acceleration of P as seen by an observer on the disk when P is at a distance of 50 ft from O .


Suppose observer is on disk at point 0 .
with $\vec{\omega}=-\Omega \hat{k}$

$$
\begin{aligned}
& \left(\overrightarrow{U p l o ~ r e ~}^{\omega}=\vec{U}_{p}-\vec{V}_{0}^{0}-\vec{\omega} \times \vec{r}_{p / 0}^{0}\right. \\
& \vec{r}_{P / D}=d \hat{b}
\end{aligned}
$$

[Same final answer it observer is at $A$ or $B$ or any point on the rotating disk.]

## Question C3.3

Sprinkler arm OA is pinned to a cart at point O. The cart moves to the right with a speed of $v_{\text {cart }}$ with $\dot{v}_{\text {cart }}=2 \mathrm{ft} / \mathrm{s}^{2}=$ constant. Fluid flows through the sprinkler arm at a rate of $\dot{d}$ with $\ddot{d}=-3$ $\mathrm{ft} / \mathrm{s}^{2}=$ constant. The sprinkler arm is being raised at a constant rate of $\dot{\theta}=4 \mathrm{rad} / \mathrm{s}$. An observer and $x y z$ coordinate system are attached to the sprinkler arm, as shown in the figure below. The following equation is to be used to find the acceleration of a pellet P that flows with the fluid in the arm:

$$
\vec{a}_{P}=\vec{a}_{O}+\left(\vec{a}_{P / O}\right)_{r e l}+\vec{\alpha} \times \vec{r}_{P / O}+2 \vec{\omega} \times\left(\vec{v}_{P / O}\right)_{r e l}+\vec{\omega} \times\left[\vec{\omega} \times \vec{r}_{P / O}\right]
$$

Provide numerical values for the following terms when: $d=3 \mathrm{ft}, v_{\text {cart }}=3 \mathrm{ft} / \mathrm{s}, \dot{d}=5 \mathrm{ft} / \mathrm{s}$ and $\theta=90^{\circ}$.

$$
\begin{aligned}
& \vec{a}_{O}=\dot{V}_{\text {cast }} \\
& \vec{\omega}=\dot{\hat{\imath}} \\
& \vec{\alpha}=\overrightarrow{0} \\
& \left(\vec{v}_{P / O}\right)_{r e l}=\dot{\alpha} \hat{\jmath} \\
& \left(\vec{a}_{P / O}\right)_{r e l}=\ddot{d} \hat{\jmath}
\end{aligned}
$$



## Question C3.4

The vertical shaft $O A$ rotates about a fixed axis with a constant rate of $\Omega=8 \mathrm{rad} / \mathrm{s}$. The arm AB is pinned to OA and is being raised at a constant rate of $\dot{\theta}=10 \mathrm{rad} / \mathrm{s}$. An observer and $x y z$ axes are attached to AB . The $X Y Z$ axes are stationary. What is the angular acceleration vector for arm AB when $\theta=90^{\circ}$ ?


$$
\begin{aligned}
& \vec{\omega}=-\Omega \hat{\sigma}+\dot{\theta} \hat{k} \\
& \left.\vec{\alpha}=-\hat{t}_{0}^{2} \hat{\sigma}-\Omega \hat{i} \hat{i}+\dot{\theta}_{0} \hat{k}+\dot{\theta} \hat{\hat{b}}\right)=\vec{\omega} \times \hat{k}
\end{aligned}
$$

Question C3.5
Arm AB rotates about a fixed vertical axis with a constant rate of $\omega_{1}$. A ring, with its center at O and of radius $r$, rotates about arm AB with a constant rate of $\omega_{2}$. A particle P moves along the ring with $\dot{\theta}=$ constant. Let the $X Y Z$ axes be fixed, and the $x y z$ axes be attached to the ring. At the position shown, $\theta=90^{\circ}$ and the $x y z$ axes are aligned with the $X Y Z$ axes. It is desired to use the following equation to determine the acceleration of P for the position shown:

$$
\vec{a}_{P}=\vec{a}_{O}+\left(\vec{a}_{P / O}\right)_{r e l}+\vec{\alpha} \times \vec{r}_{P / O}+2 \vec{\omega} \times\left(\vec{v}_{P / O}\right)_{r e l}+\vec{\omega} \times\left[\vec{\omega} \times \vec{r}_{P / O}\right]
$$

Provide expressions for the following terms appearing in this equation.


## Question C3.6

Consider an observer who is riding along on a moving (translating and rotating) rigid body. We wish to use the observation of this person in describing the motion of some point $B$, which is not fixed to the body, in the following moving reference frame acceleration equation.

$$
\begin{aligned}
\vec{a}_{B} & =\vec{a}_{A}+\left(\vec{a}_{B / A}\right)_{r e l}+\vec{\alpha} \times \vec{r}_{B / A}+2 \vec{\omega} \times\left(\vec{v}_{B / A}\right)_{r e l}+\vec{\omega} \times\left[\vec{\omega} \times \vec{r}_{B / A}\right] \\
& =\vec{a}_{A}+\vec{a}_{B / A}
\end{aligned}
$$

Answer the following questions in words:

- What is the meaning of $\vec{\omega}$ ? Ing. vel of body
- What is the meaning of $\vec{\alpha}$ ? ang-acc of body
- What is the meaning of $\left(\vec{v}_{B / A}\right)_{\text {rel }}$ ? vel. of B as seen by obscener

- What restrictions, if any, are on the choice of point A? Must be on same
n̈gid body as obsenver
- What is the difference in meaning between $\vec{a}_{B / A}$ and $\left(\vec{a}_{B / A}\right)_{\text {rel }}$ ?

$$
\vec{a}_{B / A}=\vec{a}_{B}-\vec{a}_{A} \neq\left(\vec{a}_{B / A N}=a c c \text { of } B \text { as } \operatorname{sen}\right. \text { by }
$$



