

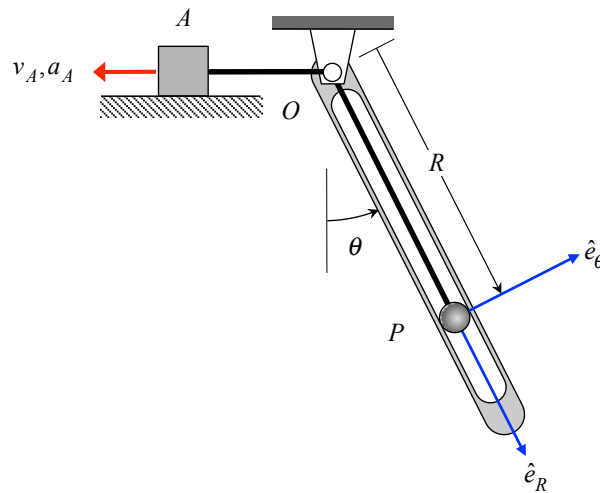
**ME 274 – Summer 2020**  
**Examination No. 1 (PM)**  
**PROBLEM NO. 1 – 20 points**

**Name** \_\_\_\_\_

**Given:** Block A moves to the left with a speed of  $v_A$  and an acceleration of  $a_A$ .  
Block A is connected to particle P with an inextensible cable, with P able to slide within a slotted arm. The arm is rotating CCW with a *constant* rate of  $\dot{\theta}$ .

- Find:** For this problem:
- Determine the velocity and acceleration vectors for point P. Write your answers using the polar unit vectors shown in the figure below.
  - Make a sketch of the velocity and acceleration vectors for P.
  - Determine the *rate of change of speed* of P.
  - Determine the *radius of curvature* for the path of P.

Use the following parameters in your analysis:  $v_A = 10 \text{ ft/s}$ ,  $a_A = 5 \text{ ft/s}^2$ ,  $\dot{\theta} = 4 \text{ rad/s}$ ,  $R = 3 \text{ ft}$  and  $\theta = 30^\circ$ .



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**PROBLEM NO. 2 – 20 points**

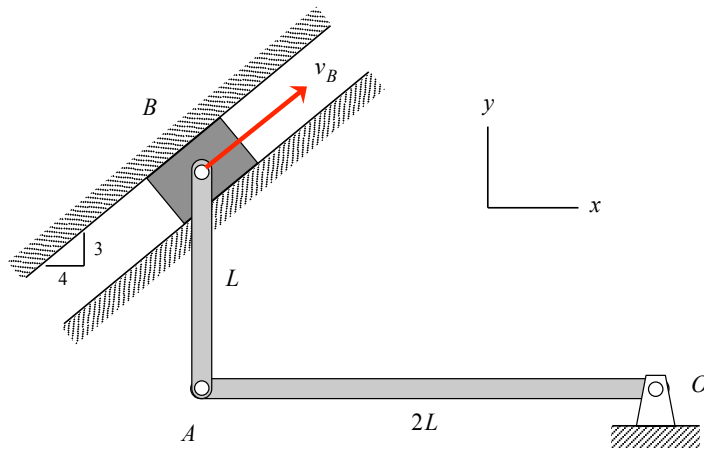
**Name** \_\_\_\_\_

**Given:** A mechanism is made up of links AB and OA, along with a sliding piston B. B moves along a straight slot with a constant speed of  $v_B$ .

**Find:** At the position shown, AB is vertical, and OA is horizontal. For this position:

- Determine the angular velocity of bar links AB and OA. Write your answers as vectors.
- Determine the angular acceleration of bar links AB and OA. Write your answers as vectors.

Leave your answers in terms of, at most,  $L$  and  $v_B$ .



**PART A – 4 points**

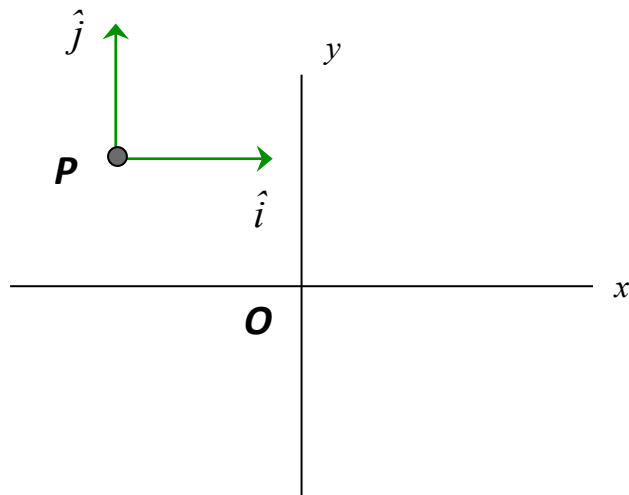
You are a passenger in automobile P. Your forward motion, in terms of the Cartesian coordinates shown in the figure, is described by the following velocity and acceleration vectors:

$$\vec{v} = (20\hat{i} - 15\hat{j}) \text{ m/s}$$

$$\vec{a} = (3\hat{i} + 5\hat{j}) \text{ m/s}^2$$

Choose the response below that most accurately describes the motion of you in the automobile:

- a) You are slowing down.
- b) You are traveling with a constant speed.
- c) You are increasing in speed.
- d) More information is needed in order to determine the characteristics of the roadway path.



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**PROBLEM NO. 3 (continued)**

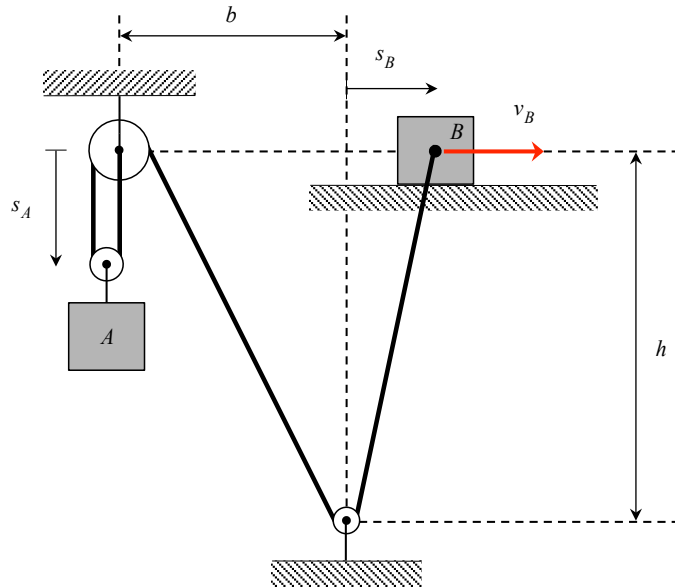
Name \_\_\_\_\_

**PART B – 4 points**

Blocks A and B are connected by an inextensible cable. B is moving to the right with a speed of  $v_B$ . Let  $v_A$  represent the speed of block A.

Choose the response below that most accurately describes the motion of A:

- a)  $v_A < v_B / 2$
- b)  $v_A = v_B / 2$
- c)  $v_B / 2 < v_A < v_B$
- d)  $v_A = v_B$
- e)  $v_A > v_B$



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**PROBLEM NO. 3 (continued)**

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**PART C – 4 points**

Consider the scaled drawing of a mechanism shown below, with the locations for the instant centers for links AB and DE are shown in the figure. Link OA is rotating CCW with an angular speed of  $\omega_{OA}$ . Let  $\omega_{AB}$ ,  $\omega_{BH}$  and  $\omega_{DE}$  represent the angular speeds of links AB, BH and DE, respectively, and let  $v_A$  and  $v_B$  represent the speeds of points A and B, respectively. Choose the correct responses in Parts C1, C2, C3 and C4 below.

**Part C1**

- a)  $\omega_{AB} = CCW$
- b)  $\omega_{AB} = 0$
- c)  $\omega_{AB} = CW$

**Part C2**

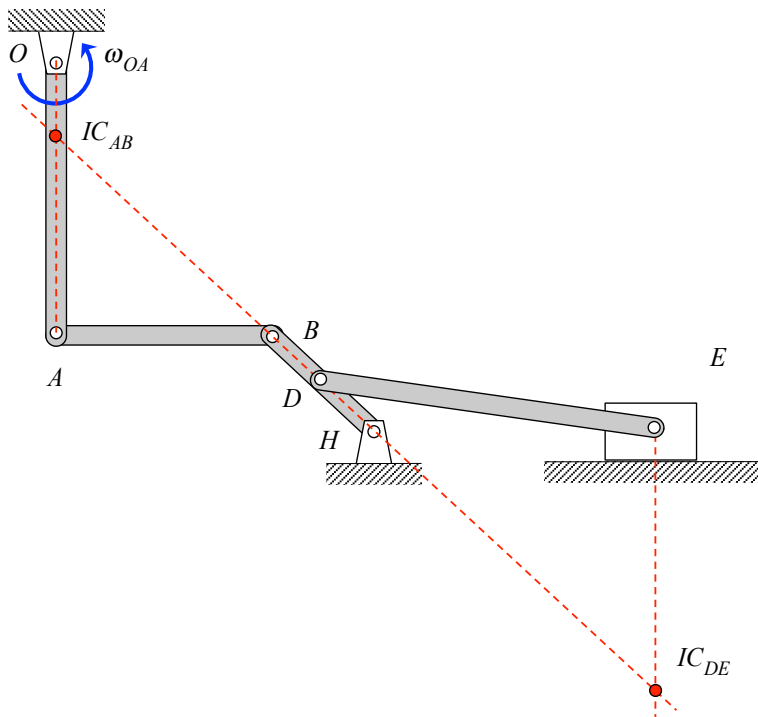
- a)  $\omega_{BH} = CCW$
- b)  $\omega_{BH} = 0$
- c)  $\omega_{BH} = CW$

**Part C3**

- a)  $\omega_{DE} = CCW$
- b)  $\omega_{DE} = 0$
- c)  $\omega_{DE} = CW$

**Part C4**

- a)  $v_A > v_B$
- b)  $v_A = v_B$
- c)  $v_A < v_B$



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**PROBLEM NO. 3 (continued)**

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**PART D – 4 points**

Consider the linkage made up of links OA and AB, with the angular orientation of these links given by the angles  $\theta_1$  and  $\theta_2$ . (Note that these angles are both measured from fixed, horizontal lines, as shown in the figure.) The constant rotation rates for these two links are given by  $\dot{\theta}_1$  and  $\dot{\theta}_2$ . The following moving reference frame kinematics equation is to be used to describe the acceleration of point B:

$$\vec{a}_B = \vec{a}_A + (\vec{a}_{B/A})_{rel} + \vec{\alpha} \times \vec{r}_{B/A} + 2\vec{\omega} \times (\vec{v}_{B/A})_{rel} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{B/A})$$

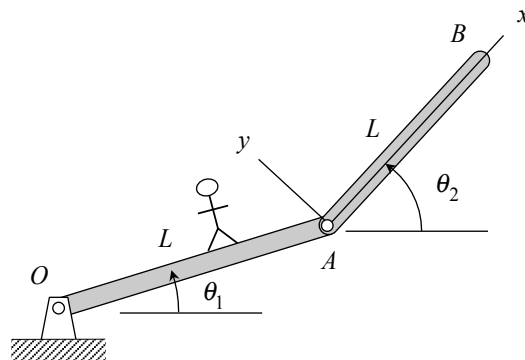
Using an observer attached to link OA, fill in the following terms below for this equation:

$$\vec{\omega} =$$

$$\vec{\alpha} =$$

$$(\vec{v}_{B/A})_{rel} =$$

$$(\vec{a}_{B/A})_{rel} =$$



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**PROBLEM NO. 3 (continued)**

***PART E – 4 points***

Aircraft A and B travel in the  $xy$ -plane, with A moving on a straight path and B moving on a circular path having a radius of 4000 ft, have velocity vectors of:

$$\vec{v}_A = (-300 \hat{i} - 400 \hat{j}) \text{ ft/s}$$

$$\vec{v}_B = (-300 \hat{i} - 600 \hat{j}) \text{ ft/s}$$

respectively. With what *speed* is B traveling as seen by an observer on aircraft A?