

Dr. Satyajit S Ambike

Department of Health and Kinesiology, Purdue University

800 West Stadium Ave, West Lafayette, IN 47907

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EDUCATION

2006-2012 Ph.D., Mechanical Engineering, The Ohio State University, OH, USA

2005-2006 M.S., Mechanical Engineering, The Ohio State University, OH, USA

1995-1999 B.E., Mechanical Engineering, University of Pune, India

CURRENT POSITIONS

- August 2023 - Present: **Associate professor**
Purdue University, West Lafayette, IN
- Co-director: Biomechanics Lab
- Research interests: Biomechanics and control of human locomotion, prehension and upper-arm movement
- August 2015 - August 2023: **Assistant professor**
Purdue University, West Lafayette, IN
- December 2019 - Present: **Faculty Associate, Center on Aging and the Life Course**
Purdue University, West Lafayette, IN

PROFESSIONAL EXPERIENCE

- March 2012 - August 2015: **Post doctoral researcher**
The Pennsylvania State University, University Park, PA

AWARDS & HONORS

- [1] Outstanding Graduate Faculty Teacher, Department of Health and Kinesiology, Purdue University, West Lafayette, IN, 2018
- [2] The Ohio State University Presidential Fellowship, Autumn 2009
 - Valued in excess of \$ 37,000
 - Awarded to about 33 students university-wide annually
 - Applicants must be nominated by their parent departments

JOURNAL PUBLICATIONS

- [1] Altenburger P, **Ambike S**, Haddad JM, 2023, "Translating Assessment of Movement Synergies to Rehabilitative Practice". *Phys Ther*, 103(10):pzad075
- [2] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, 2023, "Humans exploit passive anterior-posterior motion to improve either walking efficiency or walking stability based on environmental risk". *PLoS One*, 18(4):e0284278
- [3] Villanueva A, Jang S, Stuerzlinger W, **Ambike S**, Ramani K, 2023, "Advanced Modeling Method for Quantifying Cumulative Subjective Fatigue in Mid-Air Interaction". *Int J Hum-Comp Stud*, 169:102931
- [4] Rietdyk, S; **Ambike, S**, Amireault, S, Haddad, JM, Ling, G, Newtong, D, and Richards, EA, 2022, "Co-occurrences of fall-related factors in adults aged 60 to 85 years in the United States National Health and Nutrition Examination Survey". *PLoS One*, 17(11):e0277406
- [5] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, 2022, "Between a walk and a hard place: How stepping patterns change while navigating environmental obstacles". *Mot Control*, 27(1):20-34
- [6] Cui C, Kulkarni A, Rietdyk S, **Ambike S**, 2022, "Locomotion control during curb descent: Bilateral ground reaction variables covary consistently during the double support phase regardless of future foot placement constraints". *PLoS One*, 17(10):e0268090
- [7] Song J, Kim K, **Ambike S**, Park J, 2022, "Hierarchical and synergistic organization of control variables during the multi-digit grasp of a free and an externally fixed object". *Hum Mov Sci*, 85:102994
- [8] Naik A, **Ambike S**, 2022, "Expectation of volitional arm movement has prolonged effects on the grip force exerted on a pinched object". *Exp Brain Res*, 240:2607-2621
- [9] Cui C, Muir B, Rietdyk S, Haddad JM, van Emmerik R, **Ambike S**, 2021, "Sensitivity of the toe height to multi-joint angular changes in the lower limbs during unobstructed and obstructed gait", *J App Biomech*, 37(3):224-232
- [10] **Ambike S**, 2021, "Dynamics and stability of task-specific manifolds: Comment on 'Laws of Nature that Define Biological Action and Perception' by Mark L. Latash", *Phys of Life Rev*, 37:3-4
- [11] Kulkarni A, Cho H, Rietdyk S, **Ambike S**, 2021, "Step length synergy is weaker in older adults during obstacle crossing", *J Biomech*, 118:110311

- [12] **Ambike S**, Penedo T, Kulkarni A, Santinelli FB, Barbieri F, 2021, "Step length synergy while crossing obstacles is weaker in patients with Parkinson's disease", *Gait Posture*, 84:340-345
- [13] Cui C, Kulkarni A, Rietdyk S, Barbieri F, **Ambike S**, 2020, "Synergies in the ground reaction forces and moments during double support in curb negotiation in young and older adults", *J Biomech*, 106:109837
- [14] Naik A, **Ambike S**, 2020, "The coordination between digit forces is altered by anticipated changes in prehensile movement patterns", *Exp Brain Res*, 238:1145–1156
- [15] Tillman M, **Ambike S**, 2020, "The influence of recent actions and anticipated actions on the stability of finger forces during a tracking task", *Mot Control*, 24:365-382
- [16] Tillman M, **Ambike S**, 2018, "Expectation of movement generates contrasting changes in multifinger synergies in young and older adults", *Exp Brain Res*, 263:2765-2780
- [17] Tillman M, **Ambike S**, 2018, "Cue-induced changes in the stability of finger force-production tasks revealed by the uncontrolled manifold analysis", *J Neurophysiol*, 119:21-32
- [18] **Ambike S**, Mattos D, Zatsiorsky VM, Latash ML, 2018, "Systematic, Unintended Drifts in the Cyclic Force Produced With the Fingertips", *Mot Control*, 22:82-99
- [19] Singh T, & **Ambike S**, 2017, "A soft-contact model for computing safety margins in human prehension", *Hum Mov Sci*, 55:307-314
- [20] **Ambike S**, Mattos D, Zatsiorsky VM, Latash ML, 2016, "Unsteady steady states: Central causes of unintentional force drifts", *Exp Brain Res*, 234:3597-3611
- [21] Parsa B, **Ambike S**, Terekhov A, Zatsiorsky VM, Latash ML, 2016, "Analytical Inverse Optimization in Two-Hand Prehensile Tasks", *J Mot Behav*, 48:424-434
- [22] **Ambike S**, Mattos D, Zatsiorsky VM, & Latash ML, 2016, "Synergies in the space of control variables within the equilibrium-point hypothesis", *Neurosci*, 315:150-161
- [23] Jo HJ, **Ambike S**, Lewis MM, Huang X, & Latash ML, 2016, "Finger force changes in the absence of visual feedback in patients with Parkinson's disease", *Clin Neurophysiol*, 127:684-692, doi:10.1016/j.clinph.2015.05.023
- [24] **Ambike S**, Mattos D, Zatsiorsky VM, & Latash ML, 2016, "The nature of constant and cyclic force production: Unintentional force-drift characteristics", *Exp Brain Res*, 234:197-208
- [25] Singh T, & **Ambike S**, 2015, "A soft-contact and wrench-based approach to study grasp planning and execution", *J Biomech*, 48:3961-3967

- [26] **Ambike S**, Zhou T, Zatsiorsky VM, & Latash ML, 2015, "Moving a hand-held object: Reconstruction of referent coordinate and apparent stiffness trajectories", *Neurosci*, 298:335-356
- [27] **Ambike S**, Zatsiorsky VM, & Latash ML, 2015, "Processes underlying unintentional finger force changes in the absence of visual feedback", *Exp Brain Res*, 233:711-721
- [28] **Ambike S**, Paquet F, Zatsiorsky VM, & Latash ML, 2014, "Factors affecting grip force: Anatomy, mechanics, and referent configurations", *Exp Brain Res*, 232:1219-1231
- [29] Paquet F, **Ambike S**, Zatsiorsky VM, & Latash ML, 2013, "Enslaving in a serial chain: interactions between grip force and hand force in isometric tasks", *Exp Brain Res*, 232:775-787
- [30] **Ambike S**, Paquet F, Latash ML, & Zatsiorsky VM, 2013, "Grip-force modulation in multi-finger prehension during wrist flexion and extension", *Exp Brain Res*, 227:509-22
- [31] **Ambike S**, & Schmiedeler JP, 2013, "Invariant geometric characteristics of spatial arm motion", *Exp Brain Res*, 229:113-24
- [32] **Ambike S**, & Schmiedeler JP, 2013, "The leading joint hypothesis for spatial reaching arm motions", *Exp Brain Res*, 224:591-603
- [33] **Ambike S**, Schmiedeler JP, & Stanišić MM, 2011, "Trajectory Tracking Via Independent Solutions to the Geometric and Temporal Tracking Subproblems", *ASME J Mech Robotics*, 3(2):021008-1 - 021008-12
- [34] **Ambike S**, & Schmiedeler JP, 2008, "A methodology for implementing the curvature theory approach to path tracking with planar robots", *Mech Mach Theory*, 43:1225-1235
- [35] **Ambike S**, & Schmiedeler JP, 2007, "Application of geometric constraint programming to the kinematic design of three-point hitches", *Applied Engineering in Agriculture*, 23:13-21

PEER-REVIEWED CONFERENCE PUBLICATIONS (Full-length papers)

- [1] Jang S, Stuerzlinger W, **Ambike S**, Ramani K, 2017, "Modeling Cumulative Arm Fatigue in Mid-Air Interaction based on Perceived Exertion and Kinetics of Arm Motion", Proceedings of the 2017 CHI Conference on Human Factors in Computing Systems, Denver, CO, May 6-11
- [2] **Ambike S**, Schmiedeler JP, & Stanišić MM, 2010, "Geometric, Spatial Path Tracking Using Non-Redundant Manipulators via Speed-Ratio Control", *International Design Engineering Technical Conferences & Computers and Information in Engineering Conference, IDETC/CIE 2010*, Montreal, Canada, August 2010

- [3] **Ambike S**, Schmiedeler JP, & Stanišić MM, 2010, "Using Redundancy in Serial Planar Mechanisms to Improve Output-Space Tracking Accuracy", 12th International Symposium on Advances in Robot Kinematics, Piran-Portorož, Slovenia, July 2010
- [4] **Ambike S**, & Schmiedeler JP, 2008, "Time-invariant strategies in coordination of human reaching", *Advances in Robot Kinematics: Analysis and Design*, Ed. J. Lenarcic, P. Wenger, Springer, June 2008
- [5] **Ambike S**, & Schmiedeler JP, 2007, "First-order coordination of the articulated arm sub-assembly using curvature theory", *Proceedings of the 2007 ASME International Design Engineering Technical Conferences*, Las Vegas, September 4-7
- [6] **Ambike S**, & Schmiedeler JP, 2006, "Modeling time invariance in human arm motion coordination", *On Advances in Robot Kinematics*, Ed. J. Lenarcic, B. Roth, Kluwer Academic Publishers, June 2006

PEER-REVIEWED CONFERENCE ABSTRACTS

- [1] Prakash R, Naik G, Sullivan A **Ambike S**, 2023, Evidence of dynamic dominance in bimanual object manipulation: Grip force control. *Midwest American Society of Biomechanics*, Cleveland, OH.
- [2] Sullivan A, Naik G, Prakash R, **Ambike S**, 2023, Evidence of dynamic dominance in bimanual object manipulation: Task performance. *Midwest American Society of Biomechanics*, Cleveland, OH.
- [3] Iqbal R, Naik G, **Ambike S**, 2023, Scaling of stage-2 anticipatory synergy adjustment during finger force production in a go-no-go task. *Midwest American Society of Biomechanics*, Cleveland, OH.
- [4] Naik G, **Ambike S**, 2023, Hand-specific specialization of grip force control during bimanual manipulation. *Greater Indiana Chapter of the Society for Neuroscience (GISFN)*, West Lafayette, IN.
- [5] Song J, **Ambike S**, Shim J, Park J, 2023, Synergistic organization of control variables in control hierarchies during torque production of multi-digit prehension. *Progress in Motor Control XIV*, Rome, Italy.
- [6] Kulkarni A, **Ambike S**, Rietdyk S, 2023, Inadvertent obstacle contacts in older adults when a preferred foot placement target is available during the approach to the obstacle. *World Congress of the International Society for Gait and Posture Research (ISPGR)*, Brisbane, Australia.

- [7] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, 2023, Foot placement covariance is unaffected by an explicit target before obstacle crossing. *American Society of Biomechanics (ASB)*, Knoxville, TN, 2023.
- [8] Cui C, Kulkarni A, Rietdyk S, **Ambike S**, 2023, Anticipatory synergy adjustment during curb descent in healthy older adults. *American Society of Biomechanics (ASB)*, Knoxville, TN.
- [9] Naik A, **Ambike S**, 2023, Hand-specific specialization of grip force control during bimanual manipulation. *American Society of Biomechanics (ASB)*, Knoxville, TN.
- [10] Naik A; Iqbal R; **Ambike S**, 2023, Anticipatory synergy adjustments during finger force production scale in go-no-go tasks. *American Society of Biomechanics (ASB)*, Knoxville, TN, 2023.
- [11] Davis E, Periassamy M, Stock B, Altenburger P, **Ambike S**, Haddad JM, 2023, Using inertial measurement units (IMUs) to detect mobility changes in middle aged individuals. *The Gerontological Society of America (GSA) Annual Scientific Meeting*, Tampa, FL.
- [12] Altenburger P, **Ambike S**, Haddad JM, 2023, Using IMUs to enhance movement system assessment. Combined Sessions Meeting of the *American Physical Therapy Association (APTA)*, San Diego, CA.
- [13] Cui C, Kulkarni A, Rietdyk S, **Ambike S**, 2022, Age-related difference in margin of stability during curb descent in response to a subsequent precision stepping demand. *World Congress of the International Society for Gait and Posture Research (ISPGR)*, Montreal, Canada.
- [14] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, 2022, Stable passive dynamics during obstacle crossing may indicate a safety-energy efficiency tradeoff in older adults. *World Congress of the International Society for Gait and Posture Research (ISPGR)*, Montreal, Canada.
- [15] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, 2022, Anterior-posterior margin of stability is modulated to improve either efficiency or balance based on task demands. *Dynamic Walking*, Madison, WI.
- [16] Thompson P, Shalit EC, DeJoan AJ, Kornelik FM, Nicholson OG, Arnold JA, **Ambike S**, Claxton LJ, 2022, Evidence of Role Differentiated Bimanual Manipulation in Infants During Free-Play. *North American Society for the Psychology of Sport and Physical Activity (NASPSA)*, Hawaii.
- [17] Thompson P, DeJoan AJ, Shalit EC, Nicholson OG, Arnold JA, **Ambike S**, Claxton LJ, 2022, Impact of Toy Characteristics and Posture on Bimanual Object Interactions During Free-Play in Infants. *International Conference of Infant Studies (ICIS)*, Ottawa, Canada.

- [18] Altenburger P, **Ambike S**, Haddad JM, 2022, A Call for Advanced Motor System Assessment. Special Interest Report for the Combined Sessions Meeting of the American Physical Therapy Association (APTA), San Antonio, TX.
- [19] Cui C, Kulkarni A, Rietdyk S, **Ambike S**, 2021, Anticipatory gait adjustments during curb negotiation in response to the expectation for future stepping maneuvers. *50th Annual meeting of the Society for Neuroscience (SFN)*, Chicago, IL.
- [20] Naik A, **Ambike S**, 2021, Humans modulate gripping forces on a stationary, handheld object in response to mere expectation of rapid movement. *50th Annual meeting of the Society for Neuroscience (SFN)*, Chicago, IL.
- [21] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, 2021, Step length synergy is reduced with increasing demands on foot placement during adaptive gait. *50th Annual meeting of the Society for Neuroscience (SFN)*, Chicago, IL.
- [22] Naik A, Thompson P, Cooper A, **Ambike S**, 2021, Expectation of gait initiation alters the covariation between the horizontal ground reaction forces under the two feet. Virtual Meeting of the *American Society of Biomechanics (ASB)*, Atlanta, GA.
- [23] Cui C, Yang Z, Rietdyk S, **Ambike S**, 2021, Coordination between Vertical Ground Reaction Forces during Double Support is Different for Stair Ascent vs. Descent. *Virtual Meeting of the American Society of Biomechanics (ASB)*, Atlanta, GA.
- [24] Kulkarni A, Cui C, Rietdyk S, **Ambike S**, Barbieri FA, 2021, Effect of cognitive task on stepping parameters during expected termination. Virtual Meeting of the *American Society of Biomechanics (ASB)*, Atlanta, GA.
- [25] Naik AS, **Ambike S**, 2020, Should I stay or should I go? Stability of digit forces is lowered to enhance maneuverability when expecting to move a pinched object. *American Society of Biomechanics*, Atlanta, GA, August 4-7.
- [26] Cui C, Muir B, Rietdyk S, Haddad J, van Emmerik R, **Ambike S**, 2020, Sensitivity of Toe Height to Joint Angles of the Bipedal Linked Chain during Obstacle Crossing. *American Society of Biomechanics*, Atlanta, GA, August 4-7.
- [27] Thompson P, Cooper A, Claxton L, **Ambike S**, 2020, Structure of variance in finger forces changes with uncertainty in force tracking tasks. *American Society of Biomechanics*, Atlanta, GA, August 4-7.
- [28] Kulkarni A, Cho H, Cui C, Rietdyk S, Barbieri F, **Ambike S**, 2020, Step length synergy during adaptive gait in young adults. *American Society of Biomechanics*, Atlanta, GA, August 4-7.

- [29] Tillman MA, **Ambike S**, 2019, The stability of the current motor state is influenced by expected movement: Do cognitive events during the inter-stimulus interval of choice reaction-time tasks have a motor counterpart? *Society for Neuroscience*, Chicago, IL, October 19-23.
- [30] Naik AS, Kulkarni A, **Ambike S**, 2019, Prehensile synergies are robust to expectations of rapid upcoming movement changes. *Society for Neuroscience*, Chicago, IL, October 19-23.
- [31] Barbieri FA, Cui C, Kulkarni A, Cho H, **Ambike S**, Rietdyk S, 2019, Strategies by older adults to terminate gait unexpectedly after stepping down from a curb. *Progress in Motor Control XII*, Amsterdam, The Netherlands, July 7-11.
- [32] Kulkarni A, Cho H, Cui C, Rietdyk S, **Ambike S**, Barbieri FA, 2019, Joint angle variance in the bipedal linked chain during curb negotiation. *World Congress of the International Society for Gait and Posture Research*, Edinburgh, Scotland, June 30-July 4.
- [33] Cui C, Cho H, Kulkarni A, Rietdyk S, Barbieri FA, **Ambike S**, 2019, Synergistic ground reaction forces during double support while negotiating a curb. *World Congress of the International Society for Gait and Posture Research*, Edinburgh, Scotland, June 30-July 4.
- [34] Tillman M, **Ambike S**, 2019, Effects of Past and Future Motor Actions on Present Multifinger Pressing Behavior. International Society of Biomechanics/American Society of Biomechanics, Calgary, Canada, July 31- August 4.
- [35] Munoz-Ruiz M, Salsabili H, Tillman M, **Ambike S**, 2019, Interactions between fingers during rapid force pulse production. International Society of Biomechanics/American Society of Biomechanics, Calgary, Canada, July 31- August 4.
- [36] Cui C, Kulkarni A, Cho H, Rietdyk S, **Ambike S**, Barbieri F, 2019, Gait Termination After Stepping Down A Curb: Effect of Concurrent Cognitive task. *International Society of Biomechanics/American Society of Biomechanics (ASB/ISB)*, Calgary, Canada, July 31- August 4.
- [37] Tillman M, **Ambike S**, 2019, Effects of Past and Future Motor Actions on Present Multifinger Pressing Behavior. *Midwest Regional American Society of Biomechanics*, Dayton, OH, February 21-22.
- [38] Munoz-Ruiz M, Salsabili H, Tillman M, **Ambike S**, 2019, Interactions between fingers during rapid force pulse production. *Midwest Regional American Society of Biomechanics*, Dayton, OH, February 21-22.
- [39] Cui C, Kulkarni A, Cho H, Rietdyk S, **Ambike S**, Barbieri F, 2019, Gait termination after stepping down from a curb: Effect of concurrent cognitive task. *Midwest Regional American Society of Biomechanics*, Dayton, OH, February 21-22.

- [40] Cui C, Muir B, Haddad JM, van Emmerik R, Rietdyk S, **Ambike S**, 2018, Lower limb joint angle variance as a function of obstacle height during obstacle crossing. *American Society of Biomechanics*, Rochester, MN, August 8-11.
- [41] Tillman M, **Ambike S**, 2018, Mechanisms of preparation for task switching in a finger pressing task. *American Society of Biomechanics*, Rochester, MN, August 8-11.
- [42] Huber J, **Ambike S**, 2018, Uncontrolled manifold analysis reveals structure of variability in lip-jaw kinematics during speech production. *Neural Control of Movement*, Santa Fe, NM, May 1-4.
- [43] Salsabili H, Haddad JM, Munoz-Ruiz M, **Ambike S**, 2018, The impact of constraint severity on the coordination of simultaneous postural and manual tasks. *Progress in Clinical Motor Control and Neurorehabilitation*, University Park, PA.
- [44] Tillman M, **Ambike S**, 2017, Reduction in stability of manual behaviour in uncertain conditions. *American Society of Biomechanics*, Boulder, CO, August 8-11.
- [45] Tillman M, **Ambike S**, 2017, Uncertain Motor Plans Lower the Stability of Current Prehensile Behavior. *Midwest American Society of Biomechanics Meeting*, Grand Rapids, MI, February 23-24
- [46] Tillman M, **Ambike S**, 2017, Uncertain motor plans lead to reduced stability of the current state in young but not in older adults. *Progress in Motor Control*, Miami, FL, July 19-21
- [47] Cui C, Rietdyk S, **Ambike S**, 2017, Lower-limb joints stabilize trailing toe height during repeated obstacle crossing. *International Society of Posture & Gait Research World Congress*, Fort Lauderdale, FL, June 25-29
- [48] Liddy J, Haddad J, **Ambike S**, 2017, Increasing the Precision Demands of a Finger Force Production Task Leads to Reductions in Task-Relevant Motor Variability. *North American Society for Psychology of Sport and Physical Activity*, San Diego, CA, June 4-7
- [49] **Ambike S**, Mattos D, Zatsiorsky VM, & Latash ML, 2015, "Synergy in a space of control variables during a finger force production task", *Society for Neuroscience - Neuroscience-2015*, Chicago, USA, October 17-21
- [50] **Ambike S**, Zhou T, Zatsiorsky VM, & Latash ML, 2014, "Reconstruction of hand and grip referent trajectories during vertical oscillation of a hand-held object", *Society for Neuroscience - Neuroscience-2014*, Washington DC, USA, November 15-19

- [51] Solnik S, **Ambike S**, Wu Y-H, Reschechtko S, Latash ML, 2014, "Performance-stabilizing synergies in motor tasks involving two actors", *Society for Neuroscience - Neuroscience-2014*, Washington DC, USA, November 15-19
- [52] Reschechtko S, **Ambike S**, Qiao M, Solnik S, Zhou T, Latash ML, 2014, "Violations of equifinality under transient perturbations: The back-coupling hypothesis", *Society for Neuroscience - Neuroscience-2014*, Washington DC, USA, November 15-19
- [53] **Ambike S**, Paquet F, Latash ML, & Zatsiorsky VM, 2014, "Hand-wrist Action: Control with Referent Configurations Implemented by Complex Anatomy", *World Congress of Biomechanics*, Boston, USA, July 6-11
- [54] **Ambike S**, Paquet F, Latash ML, & Zatsiorsky VM, 2013, "Grip Force Modulation with Wrist Flexion and Extension", *Progress in Motor Control*, Montreal, Canada, July 13-16
- [55] Paquet F, **Ambike S**, Latash ML, & Zatsiorsky VM, 2013, "Interactions between Wrist Force Production and Internal Grip Force", *Progress in Motor Control*, Montreal, Canada, July 13-16
- [56] **Ambike S**, & Schmiedeler JP, 2008, "A time-invariant model for human arm motion", *Proceedings of the Fourth International Symposium on Adaptive Motion of Animals and Machines*, Cleveland, OH, June 1-6

INVITED TALKS

- [1] "Quantifying Proactive Alterations to Gait in Healthy Young and Older Adults as they Navigate Environmental Hazards". The Action Club at Pennsylvania State University, Department of Kinesiology, University Park, PA, April 14, 2023
- [2] "Adaptive Control of Locomotor Stability – A Synergy-Based Approach" The Ohio State University, Department of Mechanical and Aerospace Engineering, OH, June 29, 2022
- [3] "On the dynamic control of fingertip forces" At the workshop on Sensory Motor Control of Animals and Robots at the Mathematical Biosciences Institute, The Ohio State University, OH, November 13-17, 2017
- [4] "Age-related changes in the modulation of the stability of manual action" Feinberg School of Medicine, Northwestern University, IL, October 19, 2017
- [5] "The stability of manual action. Can we, should we stabilize fingertip forces?" Center for Cognition, Action and Perception, University of Cincinnati, OH, March 3, 2017

- [6] "The stability of manual action. Can we, should we stabilize fingertip forces?", at Purdue University, Department of Health and Kinesiology, West Lafayette, IN, December 7, 2016
- [7] "What does hand behavior reveal about motor control?", at Purdue University, Department of Mechanical Engineering, West Lafayette, IN, October 21, 2016
- [8] "Characteristics of Grip Force and Wrist Action in Humans", at University of Notre Dame, Department of Aerospace and Mechanical Engineering, South Bend, IN, September 2, 2014
- [9] "How Bizarre We Are!", A three-day lecture series on human biomechanics at Noumenon Multi-Physics, Pune, India, June 11-13, 2014
- [10] "Factors affecting grip force and wrist action", at Movement Lab, Department of Mechanical and Aerospace Engineering, The Ohio State University, Columbus, OH, March 8, 2014
- [11] "Mechanics of the Human Arm", at Indian Institute of Science and Education Research, Pune, India, February 16, 2012

INVITED TALKS ON LOCAL CAMPUS

- [1] "Manual Synergy Measurement", Technological Innovations for Optimal Aging, Center on Aging and the Life Course (CALC), Purdue University, West Lafayette, IN, September 28, 2018
- [2] "Studying Motor Function", Biology Freshman Honors Seminar, Department of Biological Sciences, Purdue University, West Lafayette, IN, September 25, 2018
- [3] "Influence of aging on stability of manual action", Purdue Institute of Integrative Neuroscience (PIIN), Purdue University, IN, June 6, 2018
- [4] "Reconstruction of referent trajectories: The case of object manipulation with the whole arm", The Motor Control Lab, Department of Kinesiology, The Pennsylvania State University, University Park, PA, September 23, 2014
- [5] "Factors affecting grip force and wrist action", at The Penn State Action Club, Department of Kinesiology, The Pennsylvania State University, University Park, PA, February 28, 2014
- [6] "Factors affecting blind, isometric, force production", at The Motor Control Lab, Department of Kinesiology, The Pennsylvania State University, University Park, PA, February 16, 2014
- [7] "An investigation into grip-force modulation during wrist flexion & extension", at The Motor Control Lab, Department of Kinesiology, The Pennsylvania State University, University Park, PA, September 17, 2013

TEACHING EXPERIENCE

PURDUE UNIVERSITY

Courses instructed:

Biomechanical Foundations of Motor Skill - Spring 2016, 2020, Autumn 2020

Advanced Topics in Kinesiology - Autumn 2016

Analysis of Human Motion - Spring 2017, 2018

Computational Methods in Biomechanics and Motor Control - Autumn 2017, 2018

Matlab for Behavior Scientists - Spring 2019, Autumn 2020

THE OHIO STATE UNIVERSITY, MECHANICAL ENGINEERING

Instructor:

Handled all responsibilities of instruction for the following subjects:

Application of Computer Graphics to Kinematic Synthesis and Analysis - Winter 2010
Graduate course focusing on advanced methods for mechanism design and analysis focusing on Burmester Theory and Curvature Theory. Class strength: 6

Kinematics and Dynamics of Machinery - Winter 2008 & Autumn 2011
Undergraduate course aiming to develop visualization and technical skills useful for the kinematic design of machinery. Class strength: 51 & 68

Teaching Assistant:

Conducted recitation sections and lab sessions for the following subjects:

Statics , Strength of Materials - Winter 2005

System Dynamics - Spring 2005, Autumn 2005, Winter 2006, Spring 2006

Principles of Automatic Control - Winter 2006

Dynamics - Spring 2011

UNIVERSITY OF PUNE, VISHWAKARMA INSTITUTE OF TECHNOLOGY, MECHANICAL ENGG.

Lecturer:

Handled all responsibilities of instruction from 2002 to 2004 for the following subjects:

Strength of Materials. Class strength: 70

Mechanical Design (design of machine components, clutches and gear box assemblies). Class strength: 30

Engineering Graphics (manual drawing and CAD systems.) Class strength: 70

ACADEMIC SERVICE

Provided guidance to undergraduate students in Kinesiology at PSU in conducting experiments involving human subjects, 2013

Served as a graduate student representative for Design on a panel for reviewing the syllabi in the Mechanical Engineering Department at OSU. The objective was to come up with recommendations based on graduate student feedback to assist the faculty in revamping the course structure for a quarter-to-semester switch undertaken by the University, 2011

Served on the OSU Mechanical Engineering faculty hiring panel, 2009. The responsibilities were to interview candidates and provide input on the candidate's proposed research and the compatibility of the individual with the work culture at OSU

Conducted presentations and lab walk-throughs for high school students, 2007

Worked as Executive Assistant in the International Cell of Vishwakarma Institute of Technology, 2004. The responsibility was to facilitate the integration of international undergraduate students with the local community.

PROFESSIONAL ACTIVITIES

GRANT REVIEWS

Served on the grant Review Panel for Clinical and Translational Sciences Institute (CTSI), Indiana, for the Surgical Instruments Small Grant, June 2018

REFEREEING

Movement Science Journal Articles: Experimental Gerontology; Neuroscience; Human Movement Science; Royal Society Open Science; Motor Control; Medicine & Science in Sports & Exercise; IEEE transactions on Haptics; PLoS One; Journal of Motor Behavior; Journal of Biomechanics; Acta Psychologica; Journal of Applied Biomechanics; Experimental Brain Research; Gait & Posture; Journal of Neurophysiology; IEEE Transactions on Neural Systems and Rehabilitation

Engineering Journal Articles: ASME Journal of Mechanisms and Robotics; ASME Journal of Machine Design; Transactions of the Canadian Society of Mechanical Engineers; Biosystems Engineering

Conferences: Intelligent Robots and Systems (IROS) 2020; IEEE International Conference on Robotics and Automation, 2014; Progress in Motor Control, 2013; ARK, 12th International Symposium on Advances in Robot Kinematics, 2010; ASME Dynamic Systems and Control Conference, 2008; American Society of Biomechanics, 2019-2022

PROFESSIONAL MEMBERSHIPS

Society for Neuroscience

International Society of Posture and Gait Research

The International Society of Motor Control

Society for the Neural Control of Movement

American Society of Biomechanics

INDUSTRY EXPERIENCE

LARSEN & TOUBRO LTD., MUMBAI, INDIA

Design Engineer: Design of heat exchangers using the ASME Boiler and Pressure Vessel Code, 2000 - 2001

Manufacturing Engineer: Shop floor engineer at a heat-exchanger manufacturing shop, 1999 - 2000

MISCELLANEOUS

COMMUNITY OUTREACH

Participated in the *Steps to Safety 5K* run for the Centre County Women's Resource Center, October 5, 2014, State College, PA

Represented India in a UN Day Dinner hosted by the United Nations Association of Centre County, October 20, 2013, State College, PA

Volunteered for the International Friendship Picnic organized by Global Connections at Penn State to welcome international scholars, September 22, 2013, State College, PA

Last updated: Wednesday 14th February, 2024